

# Efficient Bayesian Methods for Posterior Sampling and Evidence Estimation

He Jia

Peking University

# Bayes' Theorem

▷ Given model  $\mathcal{M}$ , model parameters  $\theta$  and data  $D$ ,

$$\begin{array}{c} \text{Posterior} \\ P(\theta|D, \mathcal{M}) \end{array} = \frac{\begin{array}{c} \text{Likelihood} \\ P(D|\theta, \mathcal{M}) \end{array} \begin{array}{c} \text{Prior} \\ P(\theta|\mathcal{M}) \end{array}}{\begin{array}{c} \text{Evidence} \\ P(D|\mathcal{M}) \end{array}}$$

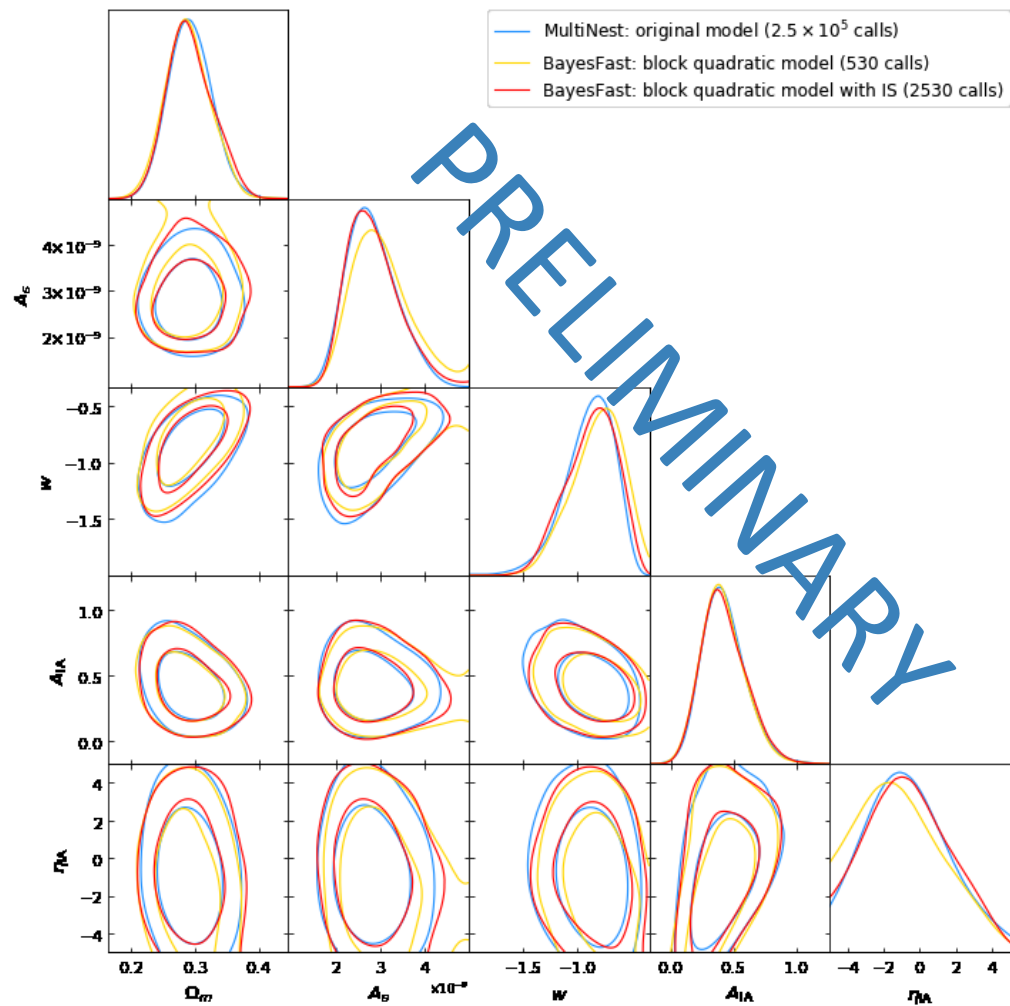
# How to get information from the posterior?

- ▷ Say we want to know  $\langle f(\theta) \rangle_p$  given the posterior  $p(\theta)$
- ▷ Naïve integration:  $\mathcal{O}(e^D)$
- ▷ In practice, we need to first get samples from  $p(\theta)$
- ▷ MCMC: typically  $10^5$  evaluations for 10-d,  $10^6$  for 20-d

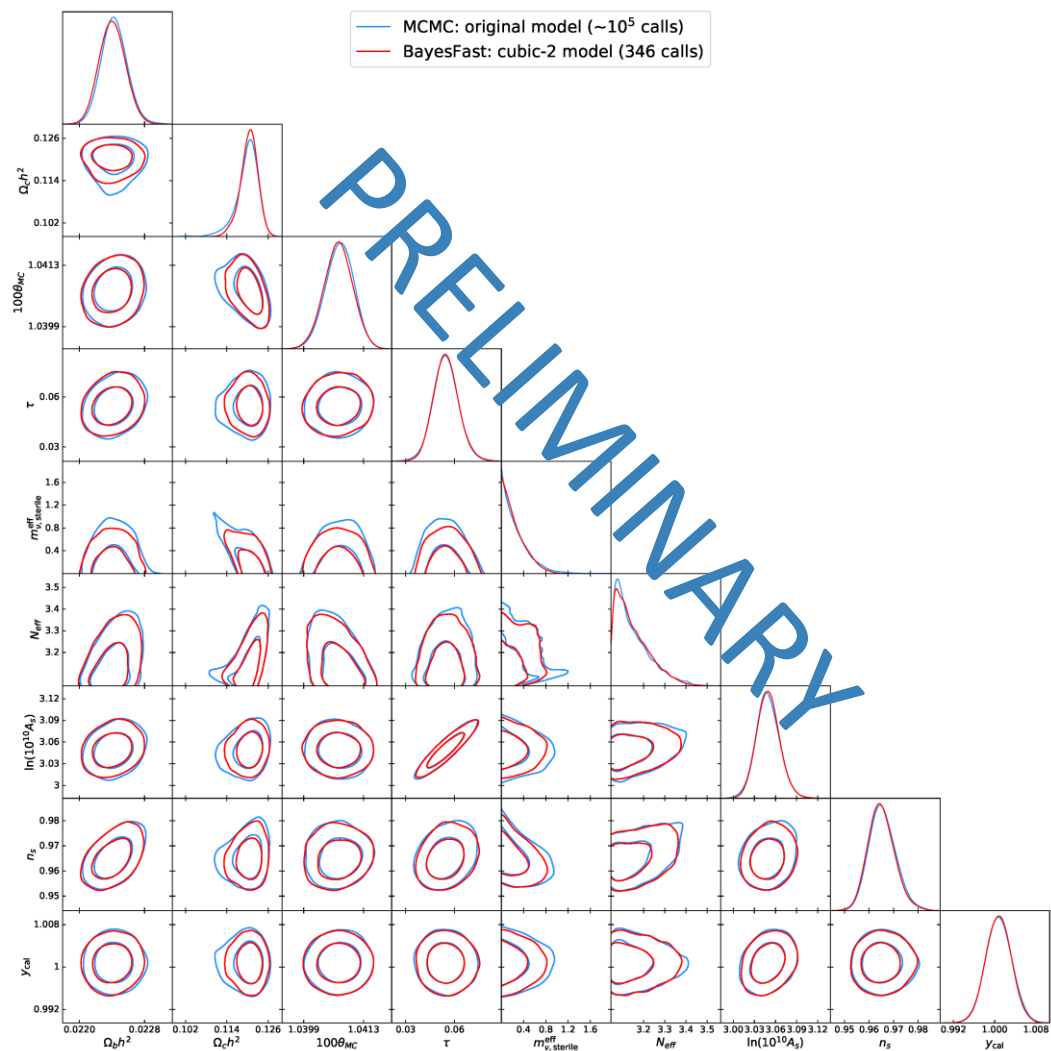
# Proposed Method

- ▷ Usually, we can write the likelihood as  $\mathcal{L}(m(\theta))$
- ▷ Only  $m(\theta)$  is expensive, so we approximate it with appropriate surrogate functions
- ▷ We found quadratic / cubic polynomials sufficient for most cosmological examples
- ▷ We can add importance weights  $p(\theta)/q(\theta)$  to retrieve asymptotic consistency

# Results: DES Year 1



# Results: Planck 2018



# Bayesian Evidence

▷ Definition:

$$p(d|\mathcal{M}) \equiv \int_{\Omega_{\mathcal{M}}} p(d|\theta, \mathcal{M})p(\theta|\mathcal{M})d\theta \quad (\text{Bayesian evidence}).$$

▷ Empirical rule for model selection:

| $ \ln B_{01} $ | Odds             | Probability | Strength of evidence |
|----------------|------------------|-------------|----------------------|
| $< 1.0$        | $\lesssim 3 : 1$ | $< 0.750$   | Inconclusive         |
| 1.0            | $\sim 3 : 1$     | 0.750       | Weak evidence        |
| 2.5            | $\sim 12 : 1$    | 0.923       | Moderate evidence    |
| 5.0            | $\sim 150 : 1$   | 0.993       | Strong evidence      |

# Proposed Method

## ▷ Bridge Sampling:

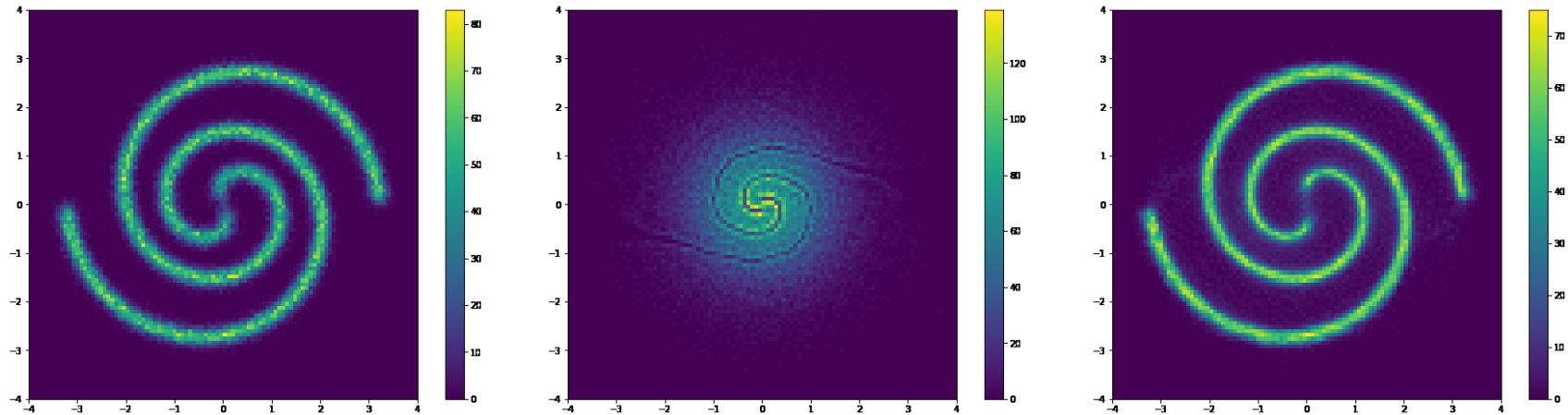
$$\int_{\Omega} \alpha(\mathbf{x}) p(\mathbf{x}) q(\mathbf{x}) d\mathbf{x} = \mathcal{Z}_p \langle \alpha(\mathbf{x}) q(\mathbf{x}) \rangle_p = \mathcal{Z}_q \langle \alpha(\mathbf{x}) p(\mathbf{x}) \rangle_q ,$$

▷ Choice of  $\alpha(x)$ : optimal bridge function can be constructed

▷ Choice of  $q(x)$ : approximated from the posterior samples

# Proposed Method

▷ Iterative Neural Transform (INT):



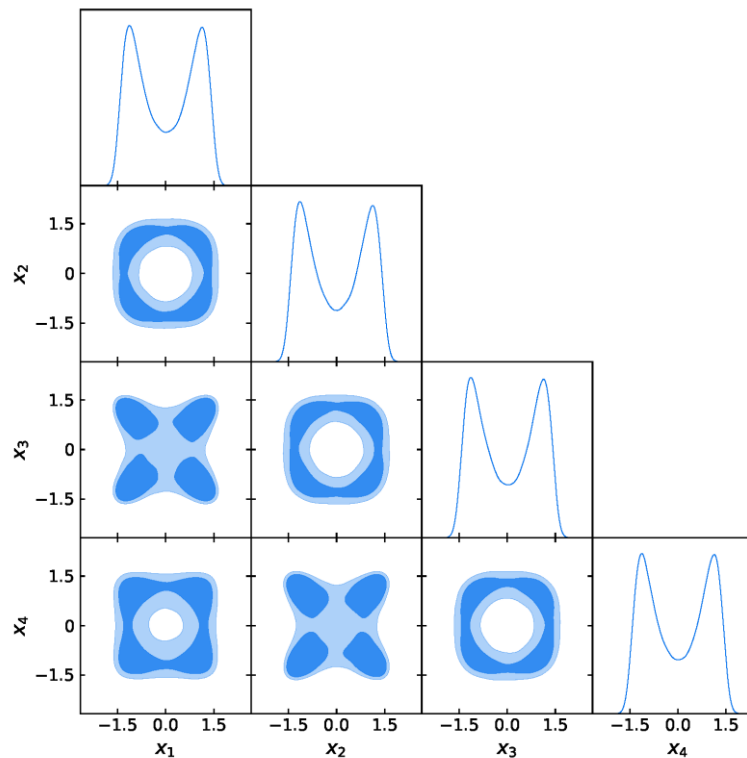
Original

Gaussianized

Generated

The details will be presented in another paper.

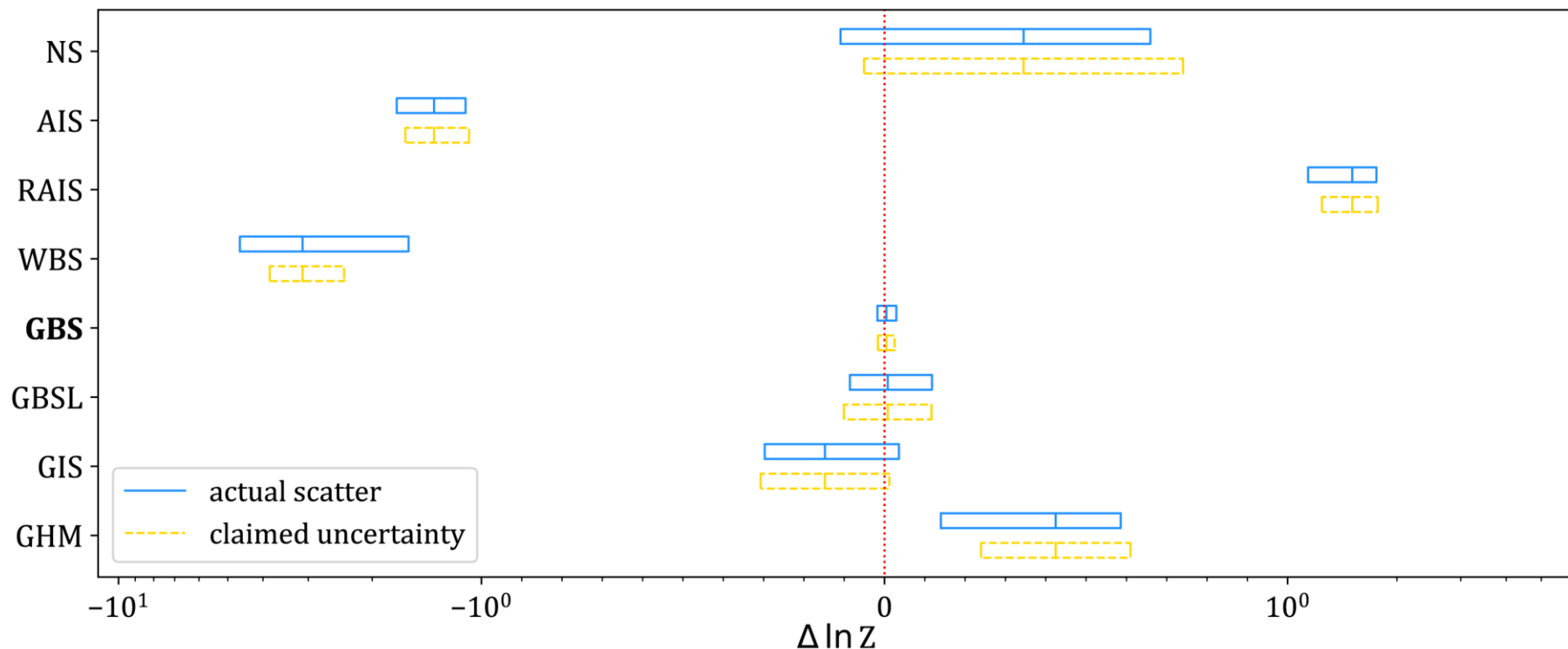
# Ring Example: Corner Plot



The example is in 64 dim. Here we only show the first 4 dim.

He Jia and Uros Seljak, *Normalizing Constant Estimation with Gaussianized Bridge Sampling*, arXiv:1912.06073.

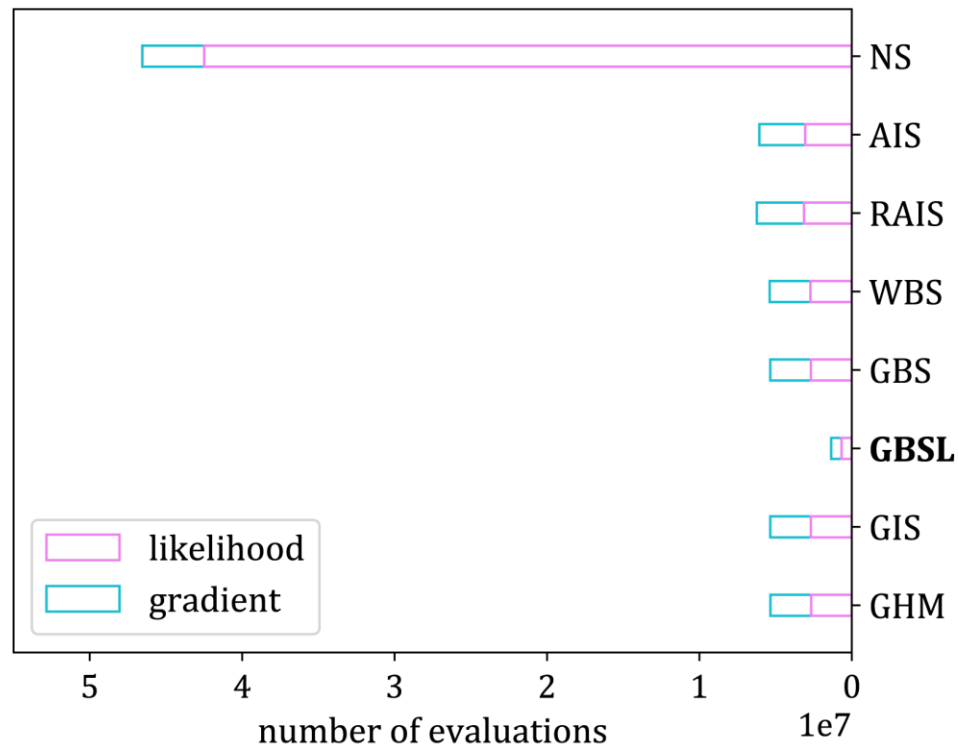
# Ring Example: Accuracy



Abbreviation keys: NS, Nested Sampling; AIS, Annealed Importance Sampling; RAIS, Reversed Annealed Importance Sampling; WBS, Warp Bridge Sampling; GBS, Gaussianized Bridge Sampling; GBSL, Gaussianized Bridge Sampling Lite; GIS, Gaussianized Importance Sampling; GHM, Gaussianized Harmonic Mean.

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# Ring Example: Computation Cost



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# Software Development

## ▷ BayesFast:

- <https://github.com/HerculesJack/bayesfast>
- Fast posterior sampling with polynomial surrogate models and No-U-Turn Sampler.
- Fast evidence evaluation with GBS algorithm.

## ▷ CosmoFast:

- <https://github.com/HerculesJack/cosmofast>
- Cosmology add-on for BayesFast.

Thanks!

**Any questions?**